

Groups 060 - 069: Throttle Valve Control

060	ESB adaption		Vehicles with ESB	
	Throttle valve angle (potentiometer)	Throttle valve angle (potentiometer)	Operating condition	Adaption condition
	[%]	[%]	Text: (Idle, partial load, full load, deceleration enrichment, acceleration enrichment)	Text: (ADP runs/ADP OK/ ERROR ^[1])
060	E-Gas adaption		Vehicles with E-Gas	
	Throttle valve angle (potentiometer 1)	Throttle valve angle (potentiometer 2)	Electrically controlled throttle valve adaption status	Operating condition
	[%]	[%]	[n]	Text: ADP runs/ADP OK/ ERROR
061	ESB/E-Gas		Systems without separation for rear window defroster /A/C readiness	
	RPM	Supply voltage Ubat	Triggering throttle valve control	Operating condition
	[1/min]	[V]	[%] if possible	0xxx ^[2] <ul style="list-style-type: none"> └─ A/C compressor ON └─ driving range selected └─ A/C readiness/ rear window defroster ON └─ always 0
061	ESB/E-Gas		Systems with separation for rear window defroster /A/C readiness	
	RPM	Supply voltage Ubat	Actuating throttle valve control	Operating condition
	[1/min]	[V]	[%]	xxxx 15 <ul style="list-style-type: none"> └─ A/C compressor ON └─ driving range selected └─ A/C readiness ON └─ Rear window defroster ON
062	E-Gas, potentiometer voltage relationship U/U _{ref}			
	Angle sensor 1 for throttle valve drive (0->100%)	Angle sensor 2 for throttle valve drive (0->100%)	Sensor 1 accelerator pedal position (0->100%)	Sensor 2 accelerator pedal position (0->100%)
	[%]	[%]	[%]	[%]
063	Kick-down adaption			

	Sensor 1 accelerator pedal position (0->100%) [%]	Sensor 1 learned Kick-down point (0->100%) [%]	Switch Kick-down	Result Actuated; ADP runs; ADP OK; ERROR
064	Throttle valve potentiometer adaption values			
	Potentiometer 1 lower adaption [V]	Potentiometer 2 1 lower adaption [V]	Emergency air gap potentiometer 1 [V]	Emergency air gap potentiometer 2 [V]
065				
066	Cruise control switched free for 4 position operating lever			
	Vehicle speed actual [km/h]	Switch positions xxxxxxx Lbrake light switch Pedal pressed Lbrake pedal switch Pedal pressed Lclutch switch Pedal pressed LCC function switched free LADR-Function switched free not used 00 ADR/CC not active (also used for not installed) 01 ADR/CC in control mode 10 Condition „over controlled“, driver accelerates more than cruise control regulator 11 ADR not released 1: Condition fulfilled 0: Condition not fulfilled	Vehicle speed specified [km/h] in 1 km/h-steps (only displayed when cruise control function is freely switched)	Switch positions For 4 position operating lever xxxxxxx LCC ON / OFF Lmemory set /CC OFF LSet /tip down / decelerate LResume / Tip up/ acceleration ----0000 CC engaged OFF ----0001 CC tipped OFF ----0011 CC engaged ON (stand by) ----01x1 Set/Tip down/ decelerate ----1011 Resume/Tip up/ accelerate
066	Cruise control switched free for 6 position operating lever			
	Vehicle speed actual	Switch positions	Vehicle speed specified	Switch positions

	[km/h]	<p>xxxxxxx</p> <p> L brake light switch</p> <p> Pedal pressed</p> <p> L brake pedal switch</p> <p> Pedal pressed</p> <p> L clutch switch</p> <p> Pedal pressed</p> <p> L CC function switched free</p> <p> L ADR function switched free</p> <p> not used</p> <p>00 ADR/ CC not active (also used for not installed)</p> <p>01 ADR/ CC in control mode</p> <p>10 Condition „over-controlled“, driver accelerates more than cruise control regulator</p> <p>11 ADR not released</p> <p>1: Condition fulfilled</p> <p>0: Condition not fulfilled</p>	[km/h]	<p>For 6 position operating lever</p> <p>xxxxxxx</p> <p> LCC ON /OFF engaged</p> <p> (CAN) LCC tipping, yes/no</p> <p> Memory set</p> <p> L Tip down / decelerate</p> <p> L Tip up/ accelerate</p> <p> L Set</p> <p> L Resume</p> <p>L CC ON/OFF engaged (Hardware PIN)</p> <p>0-000000 CC engaged OFF</p> <p>1-000001 CC engaged ON (stand-by)</p> <p>1-000011 CC tipped OFF</p> <p>1-000101 Tip down/decelerate</p> <p>1-001001 Tip up/accelerate</p> <p>0-010000 Set (with CC engaged OFF)</p> <p>1-010001 Set (with CC engaged ON)</p> <p>1-100001 Resume</p>
067				
068				
069				

[1] ADP ERROR = in emergency mode

[2] Condition fulfilled = 1; Condition not fulfilled = 0